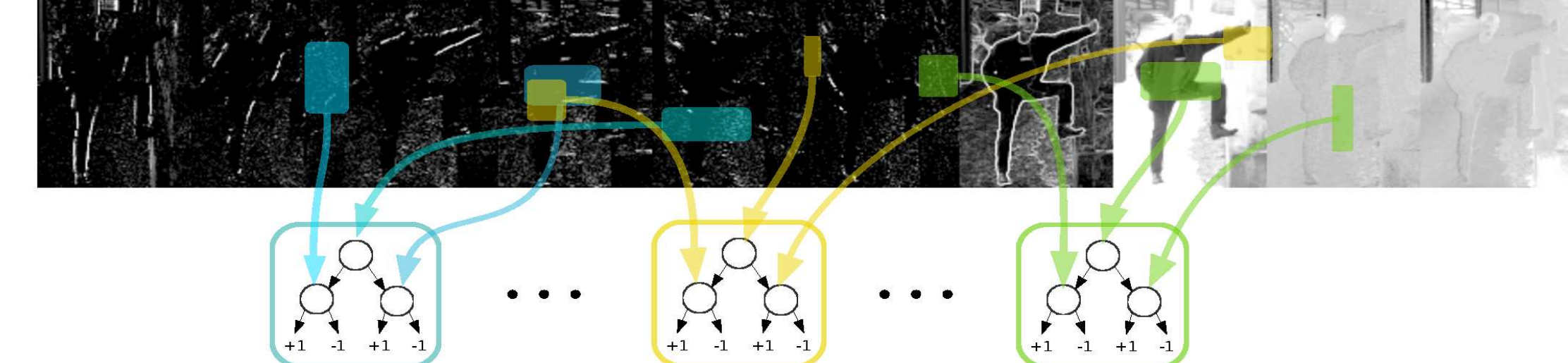


Background

We build upon: HOG & Color + Adaboost [1, 3, 5]

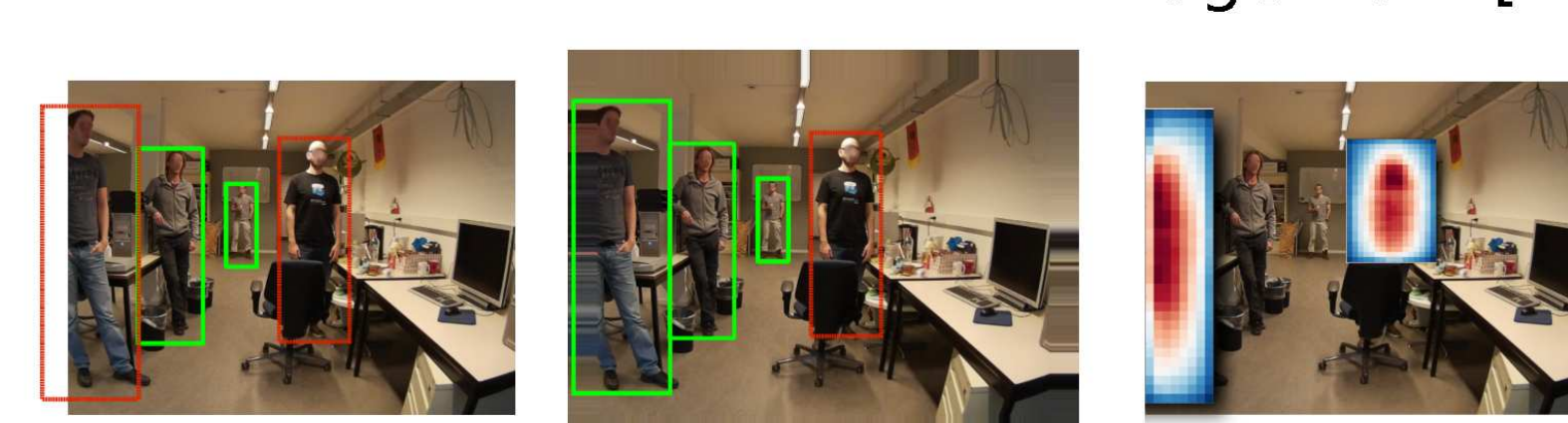
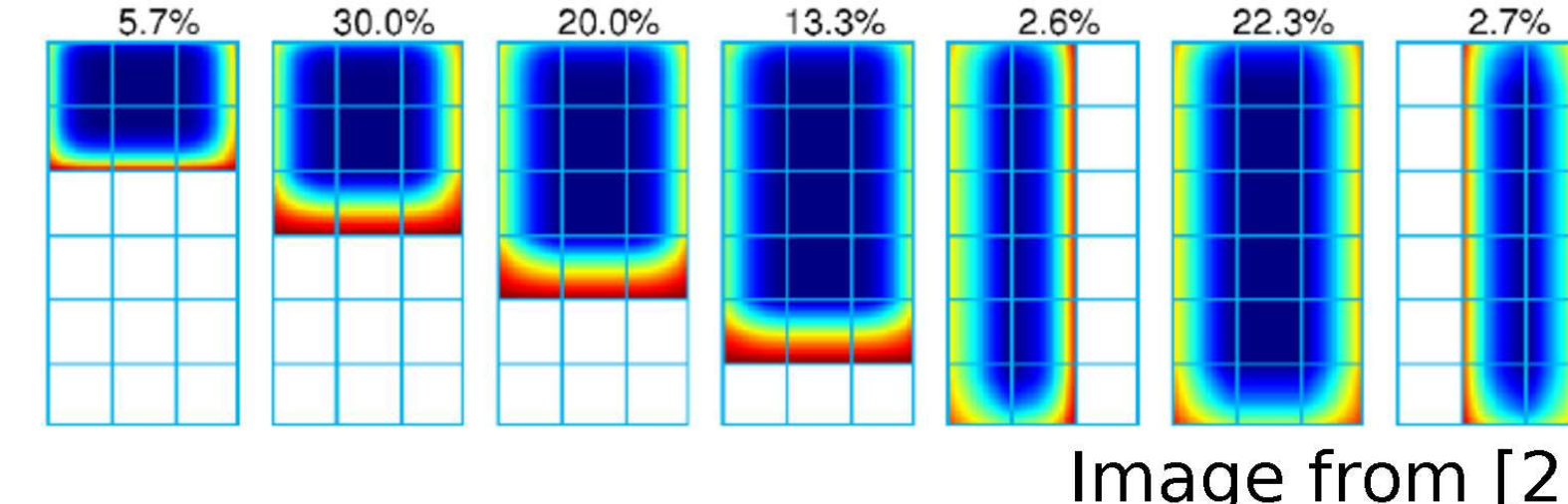


Training a model with 2000 weak learners and 3 iterations of bootstrapping takes ~ 60 min

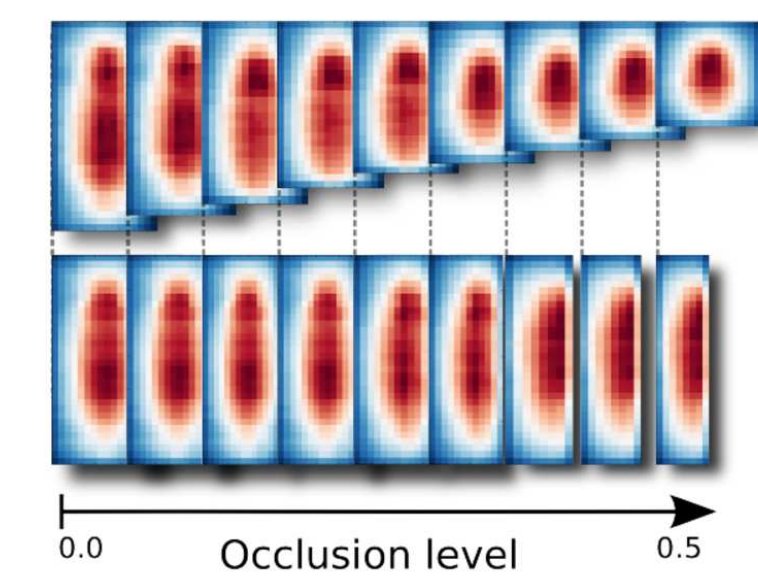


Motivation

- Occlusions occur frequently
- 97% of occlusion cases are covered by a small subset of occlusion types [2]
- Approaches:
 - Most top performing methods do not handle occlusions explicitly; occlusions from the image border by border extrapolation
 - Train joint model for object + occluder
 - Train occlusion specific models, usually only 3~5



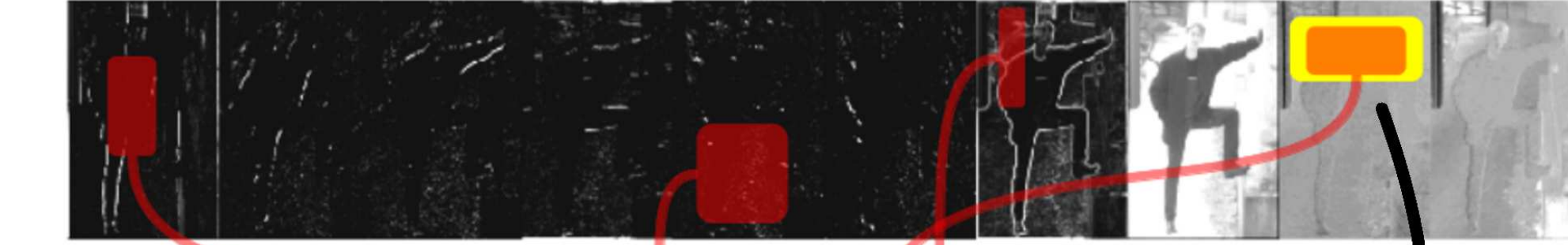
We train 16+8+8+1=33 occlusion specific classifiers for different types and levels of occlusion



Key insight

- Feature pool huge, many features with similar errors
- AdaBoost algorithm is greedy: worse choices at one point may not affect quality
- Boosting compensates for bad choices

Can we bias the selection of features?



Set of features with similar errors

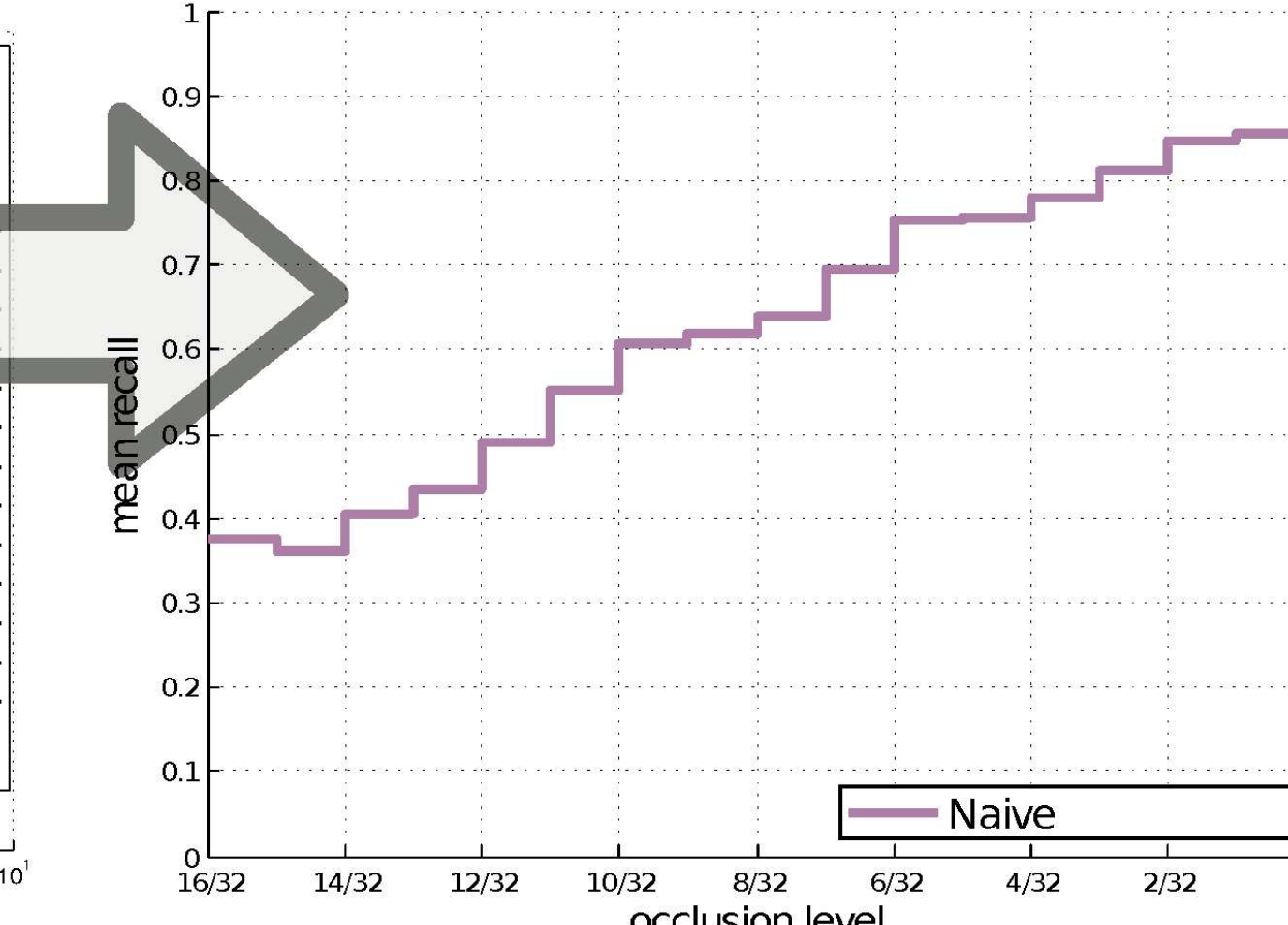
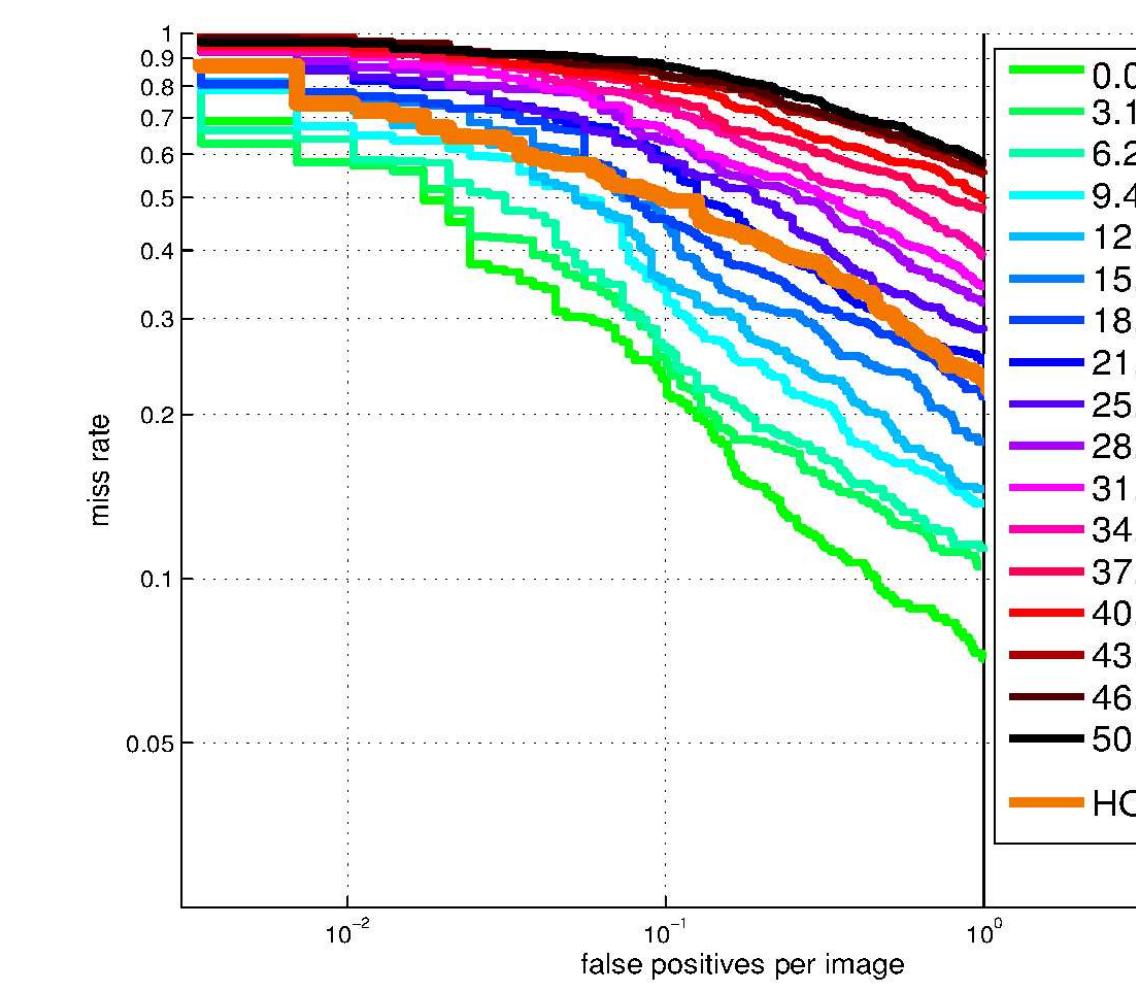
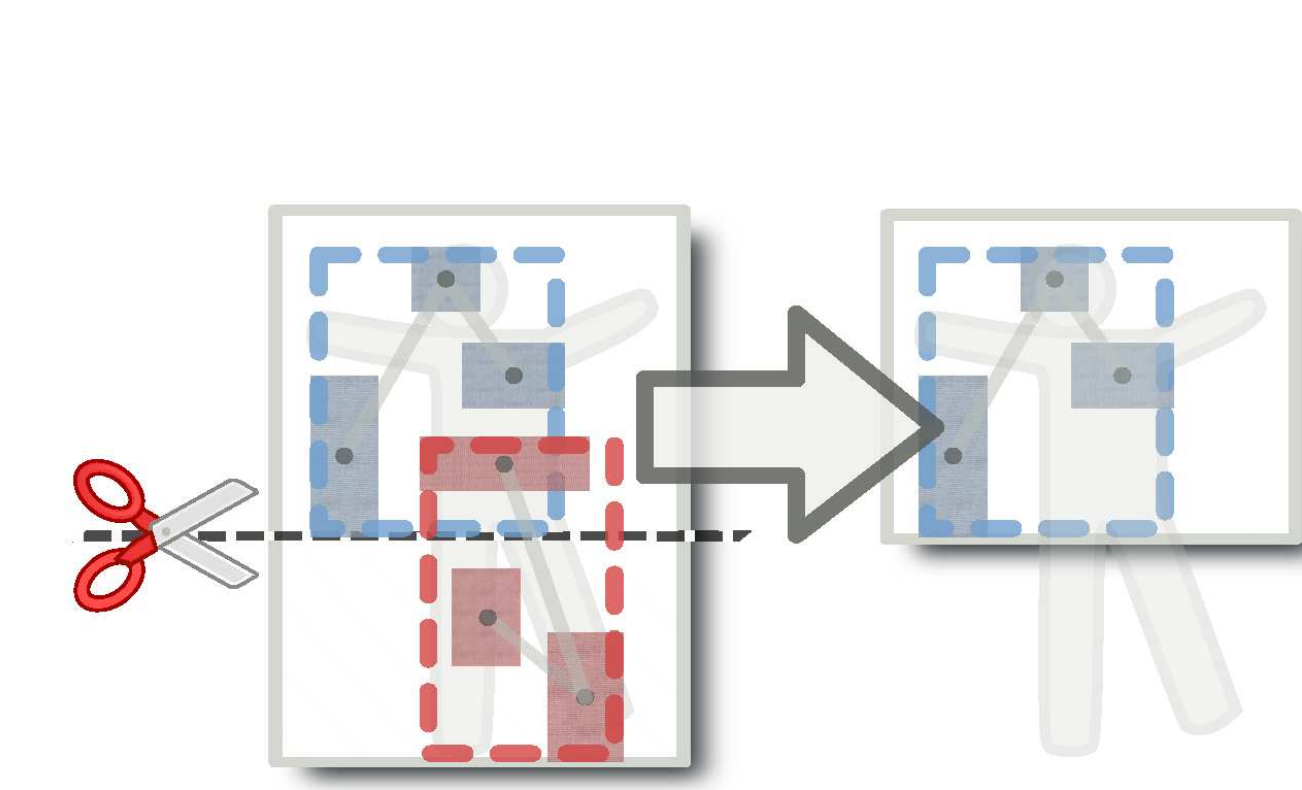
Select the most suitable feature rather than the best feature

References

- [1] N. Dalal and B. Triggs. Histograms of oriented gradients for human detection. CVPR 2005
- [2] P. Dollár, C. Wojek, B. Schiele, and P. Perona. Pedestrian Detection: An Evaluation of the State of the Art. TPAMI, 2011
- [3] P. Dollár, Z. Tu, P. Perona, and S. Belongie. Integral channel features. BMVC 2009
- [4] R. Benenson, M. Mathias, R. Timofte, and L. Van Gool. Pedestrian detection at 100 frames per second. CVPR 2012
- [5] R. Benenson, M. Mathias, R. Timofte, Tinne Tuytelaars, and L. Van Gool. Seeking the strongest rigid detector. CVPR 2013

A. Naive approach: Cutting classifiers

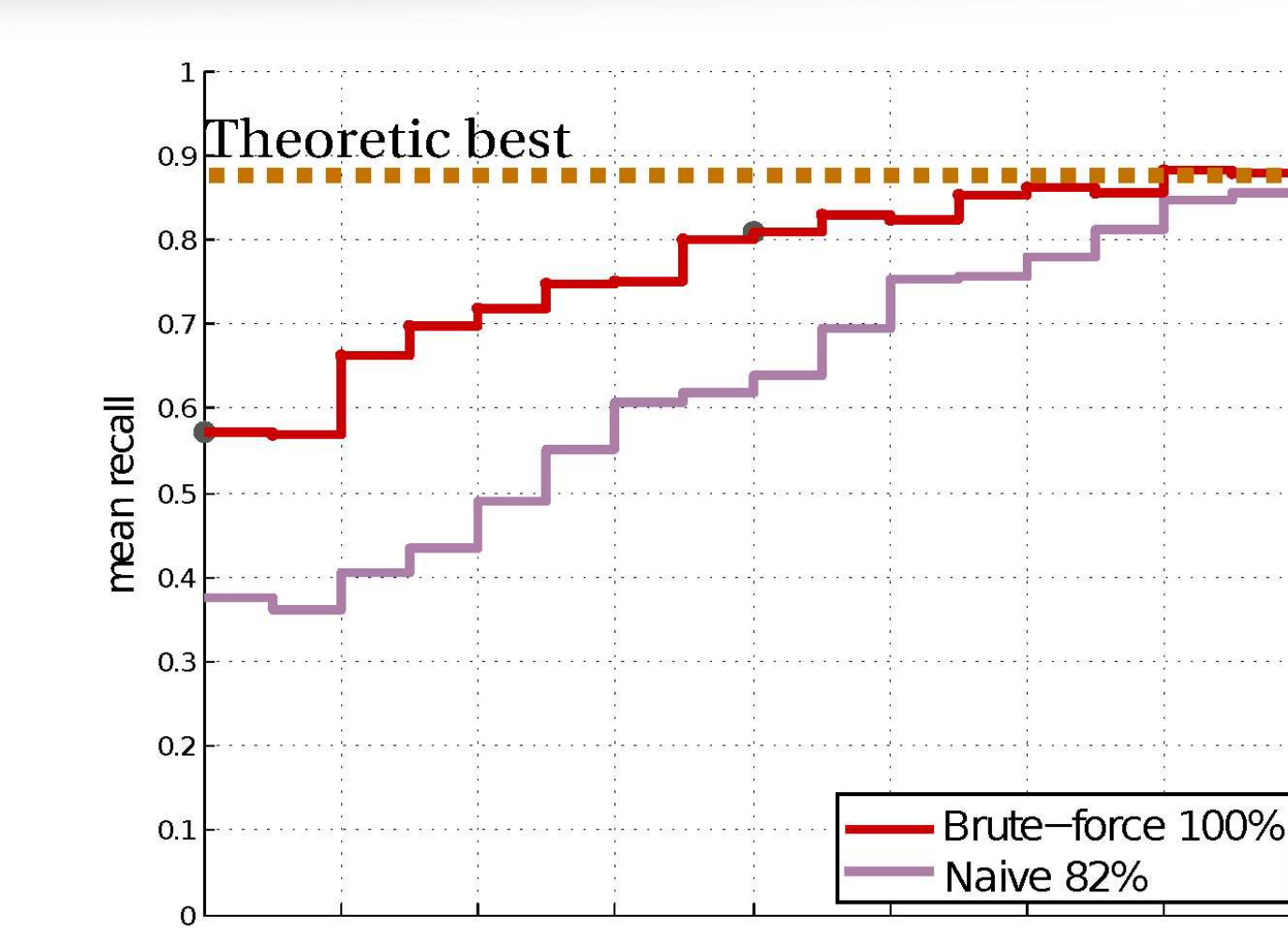
- For each classifier run full evaluation on INRIA dataset



Low quality

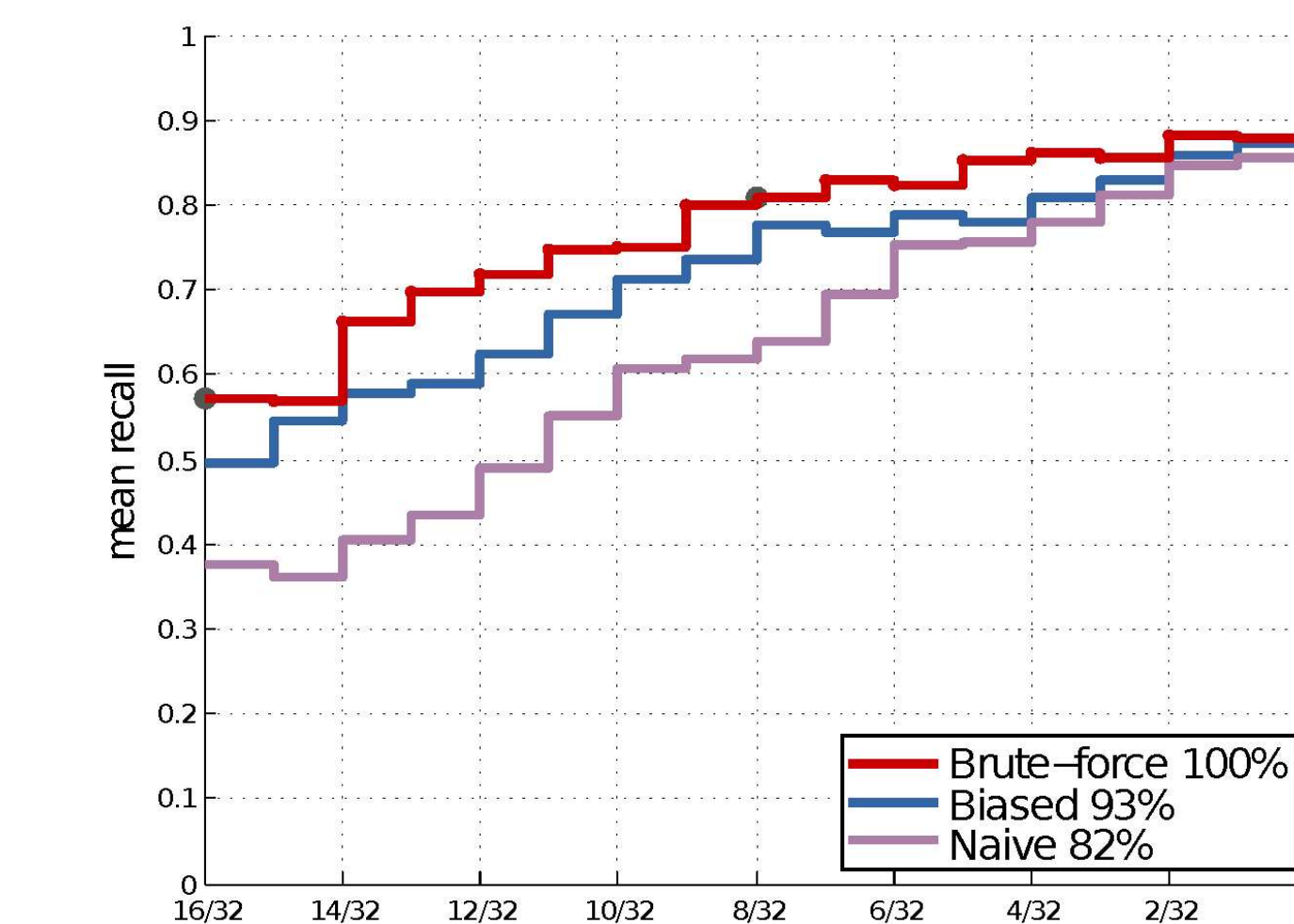
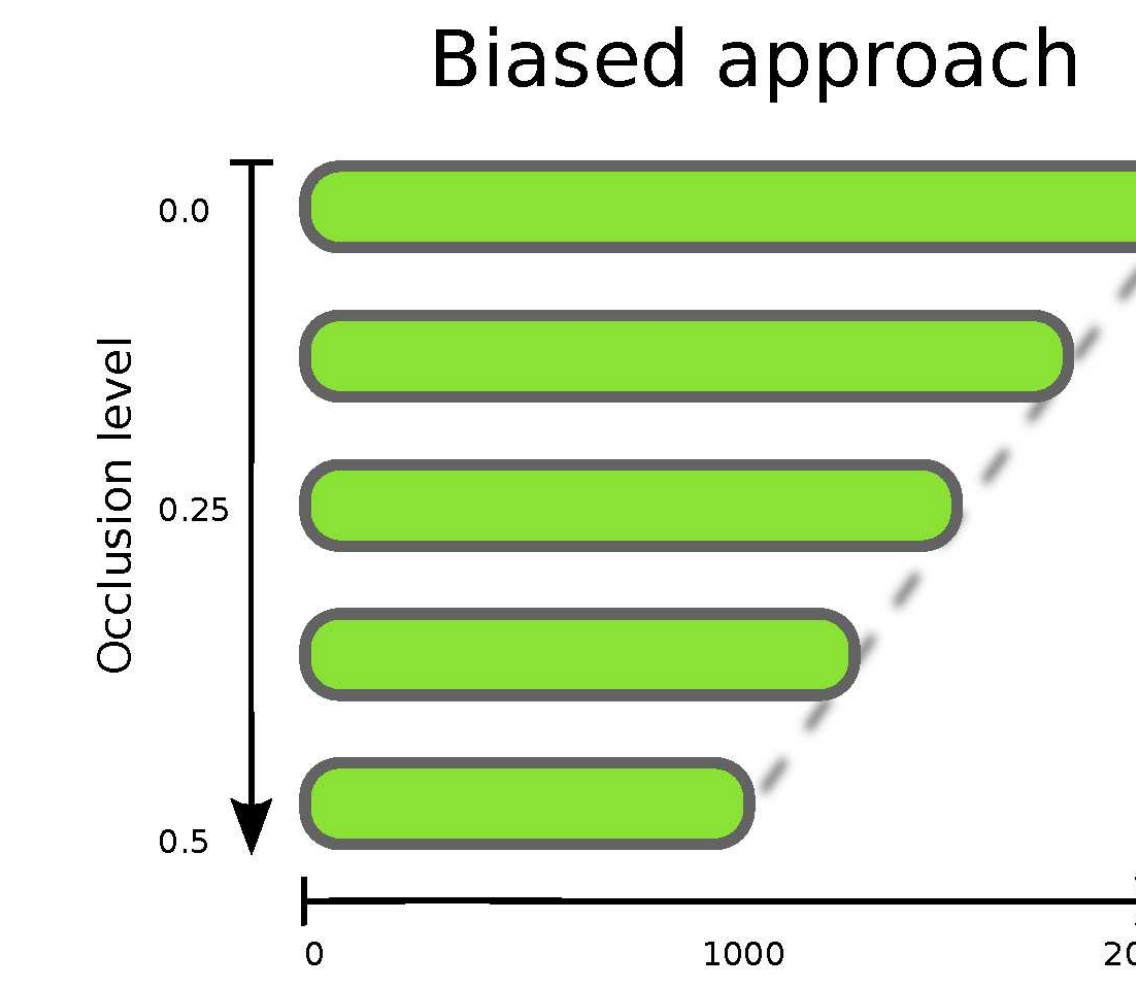
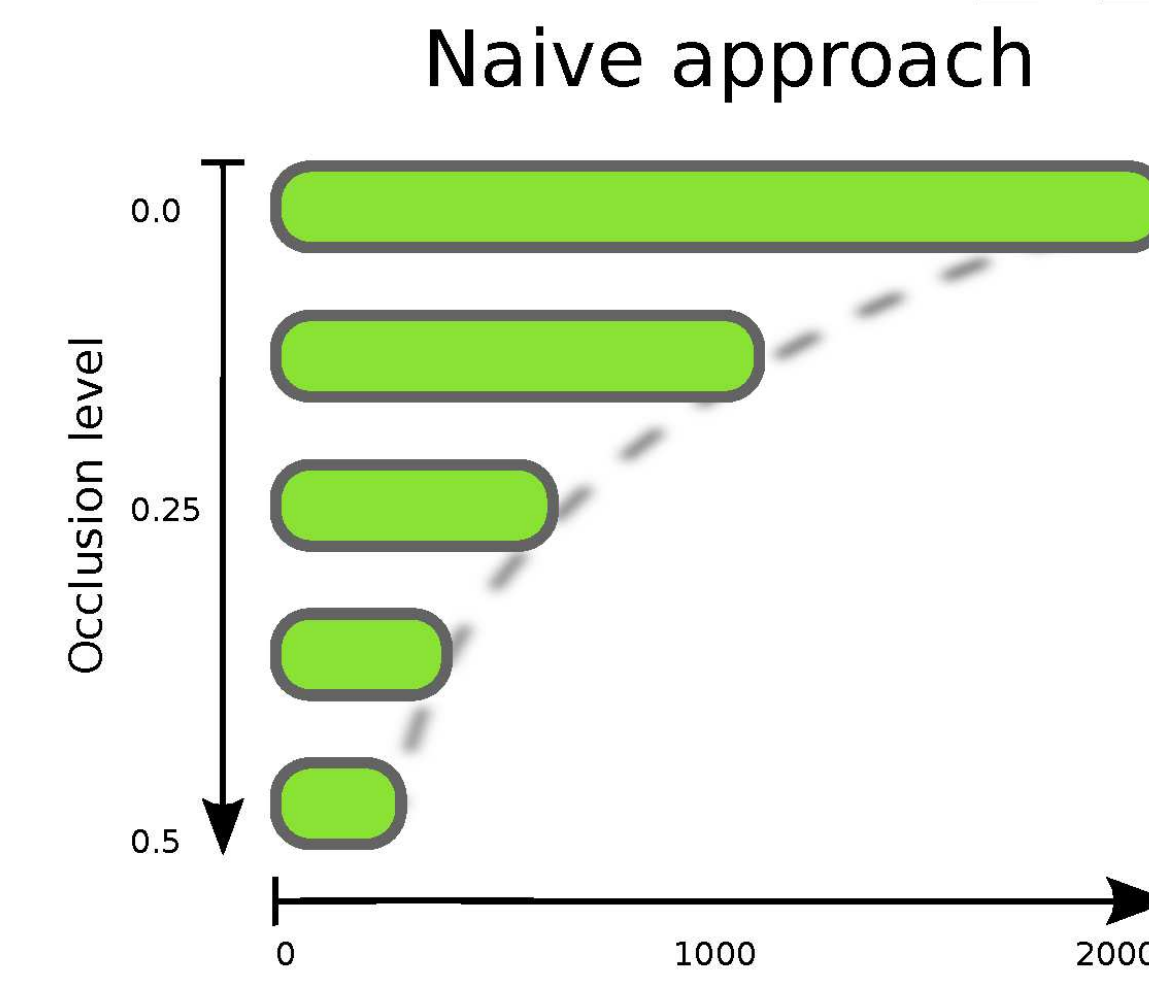
B. Brute force classifiers

- Train classifier for each possible occlusion level
- Theoretic best outcome: half pedestrian classifier performs as good as the full pedestrian classifier



High quality

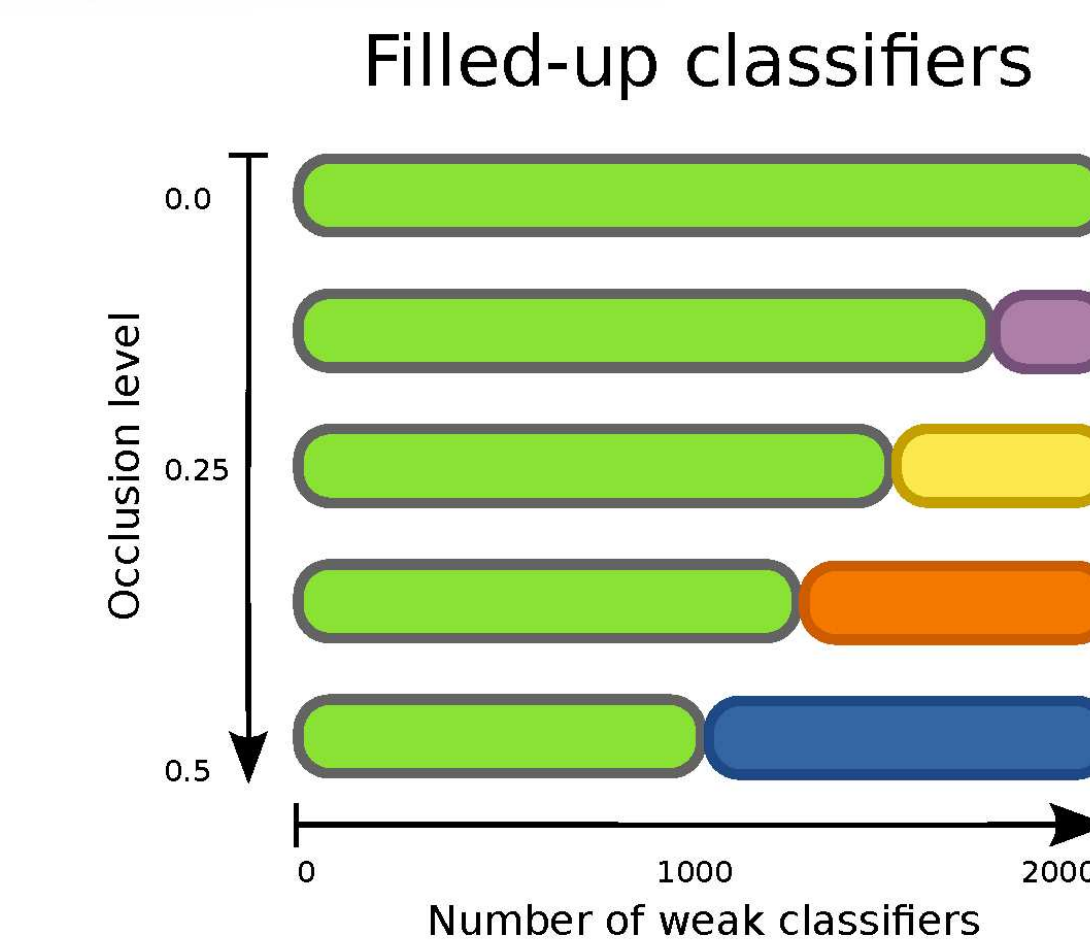
C. Biased approach: Cutting biased classifiers



Medium quality

D. Fill-up classifiers

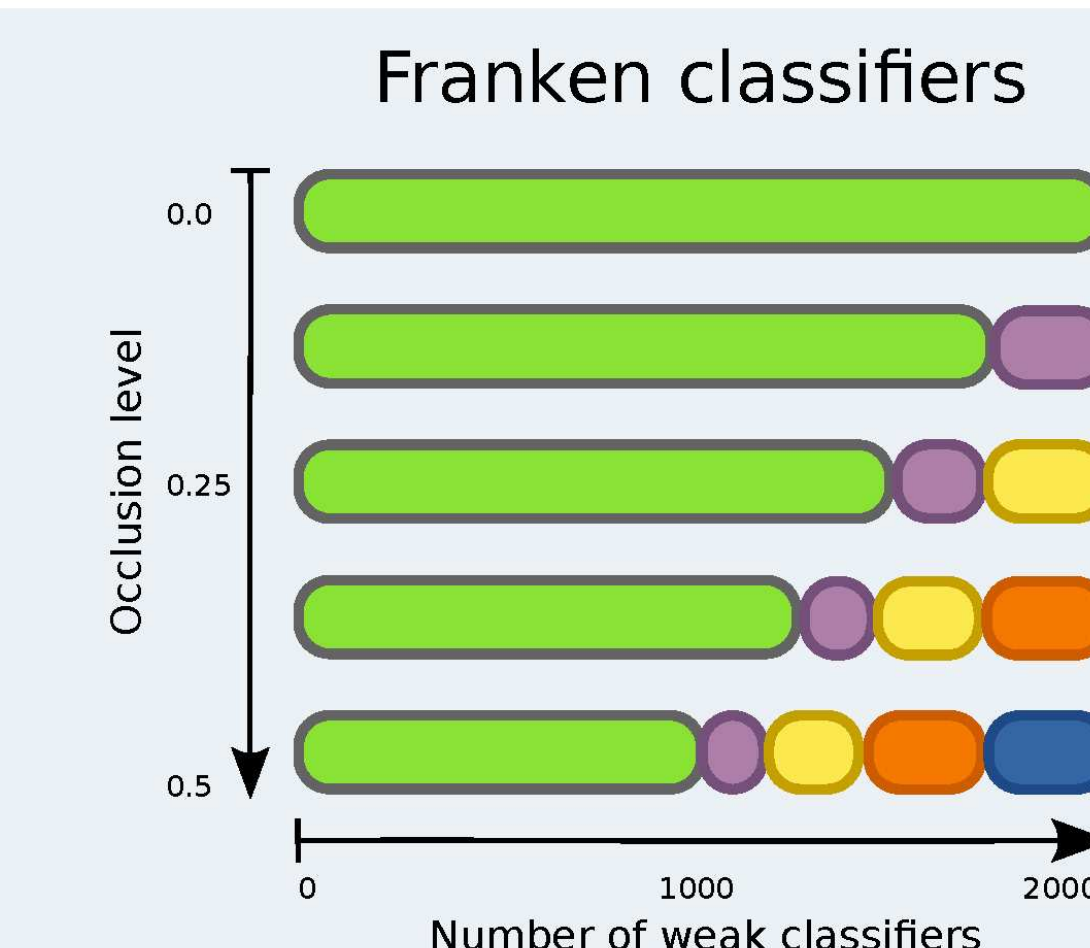
- Train a Biased classifier as basis
- Number of weak learners as proxy for quality
- Train additional features for each occlusion level



High quality

E. Franken-classifiers

- Train a Biased classifier as basis
- Train Fill-up classifiers in a recursive way
- Classifier of the last (most drastic) occlusion level will potentially have weak classifiers from all previous occlusion levels, hence the name Franken-classifiers



High quality

Contributions

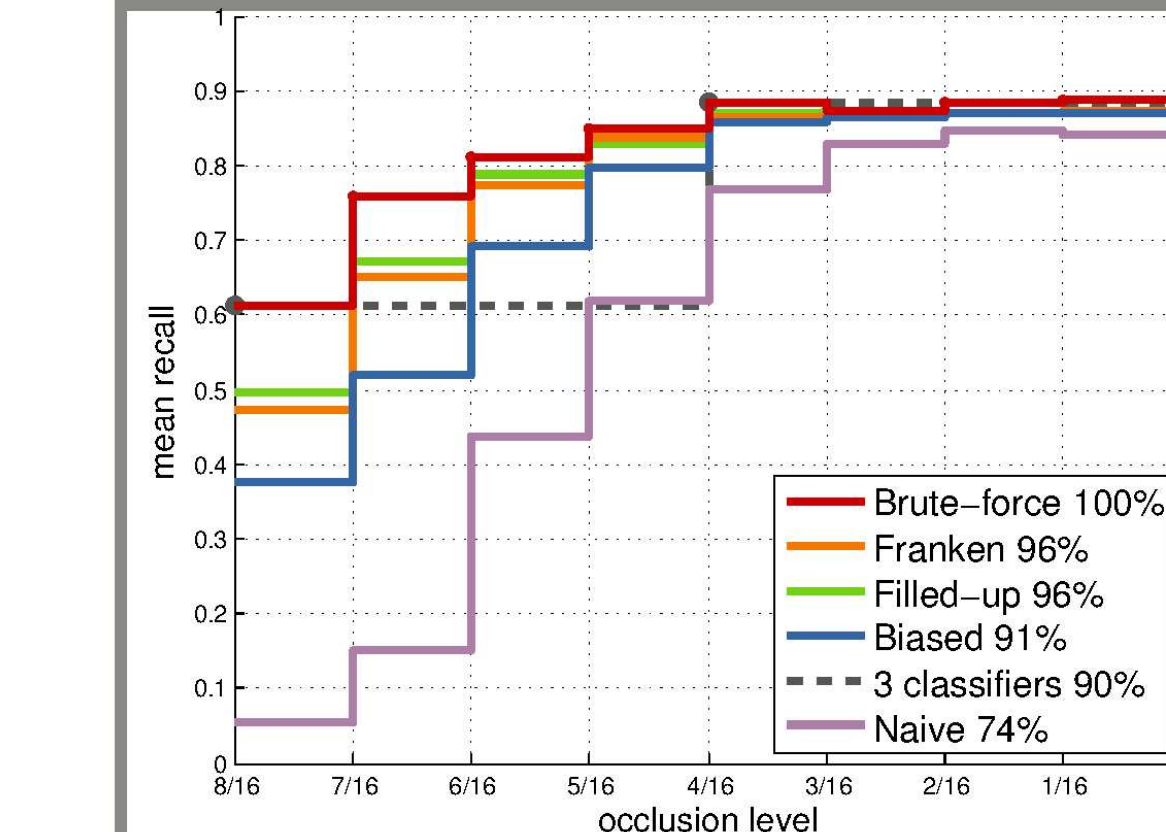
- We show that the Integral Channel Features Detector family is brittle under **occlusion** ([3,4,5])
- Concept of **biasing AdaBoost** training biased on a spatial criterion
- Franken classifiers with **sub-linear** cost for training and testing (to number of classifiers)
- Franken classifiers are **generic** and provide **state-of-the-art results** under occlusion

Results

How good is each occlusion specific classifier?

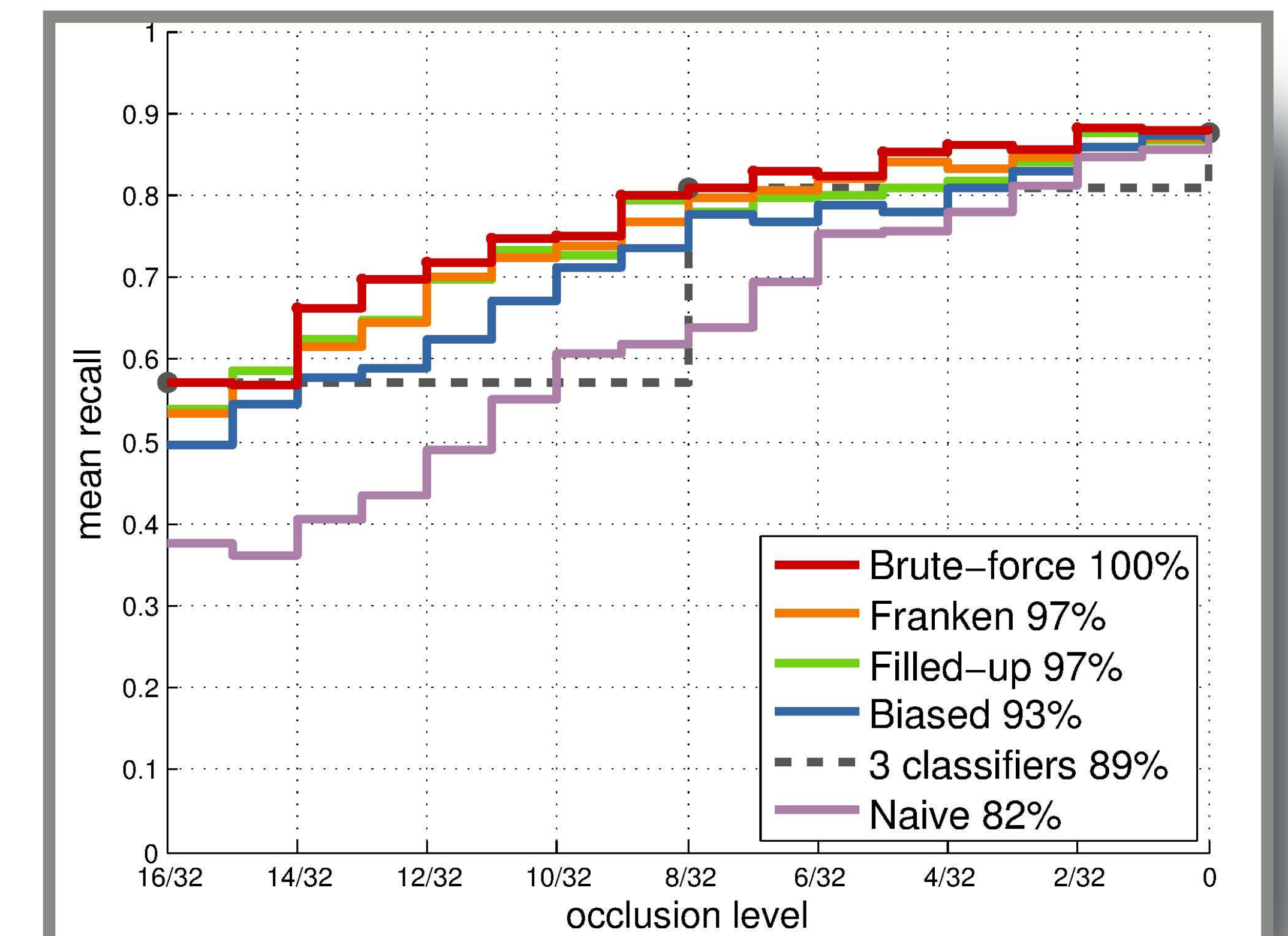
- Usage e.g. on the image border, depth discontinuities, around cars...
- More efficient than border extrapolation

Right occlusion



Type	Number of classifiers	Quality	Relative training time	Training time in minutes
Brute-force	17	100%	100%	1088
5 classifiers	5	94%	29%	320
3 classifiers	3	89%	18%	192
Franken	1+16	97%	8%	64+28
Filled-up	1+16	97%	11%	64+54
Biased	1+16	93%	6%	64
Naive	1+16	82%	6%	64

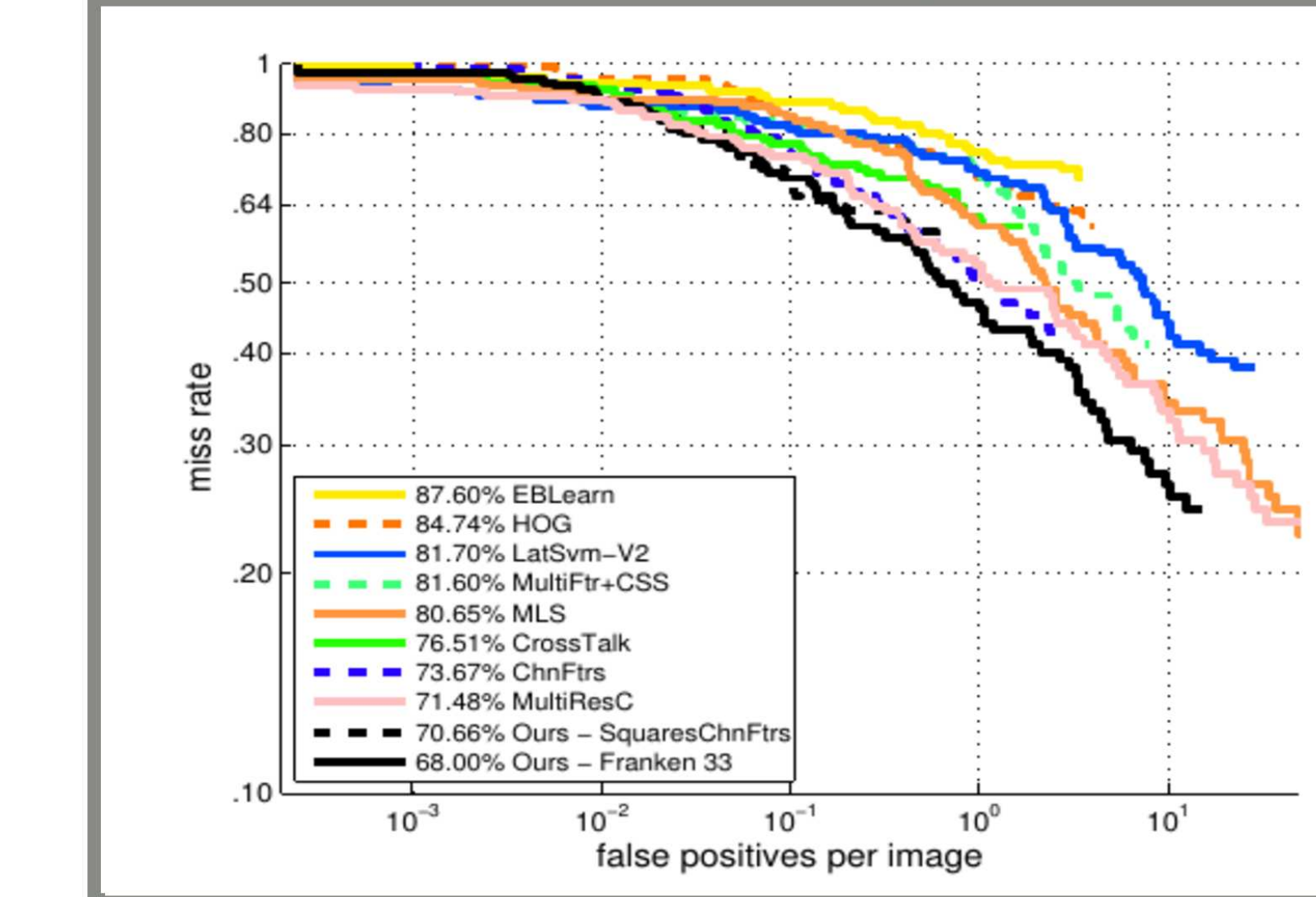
Bottom occlusion



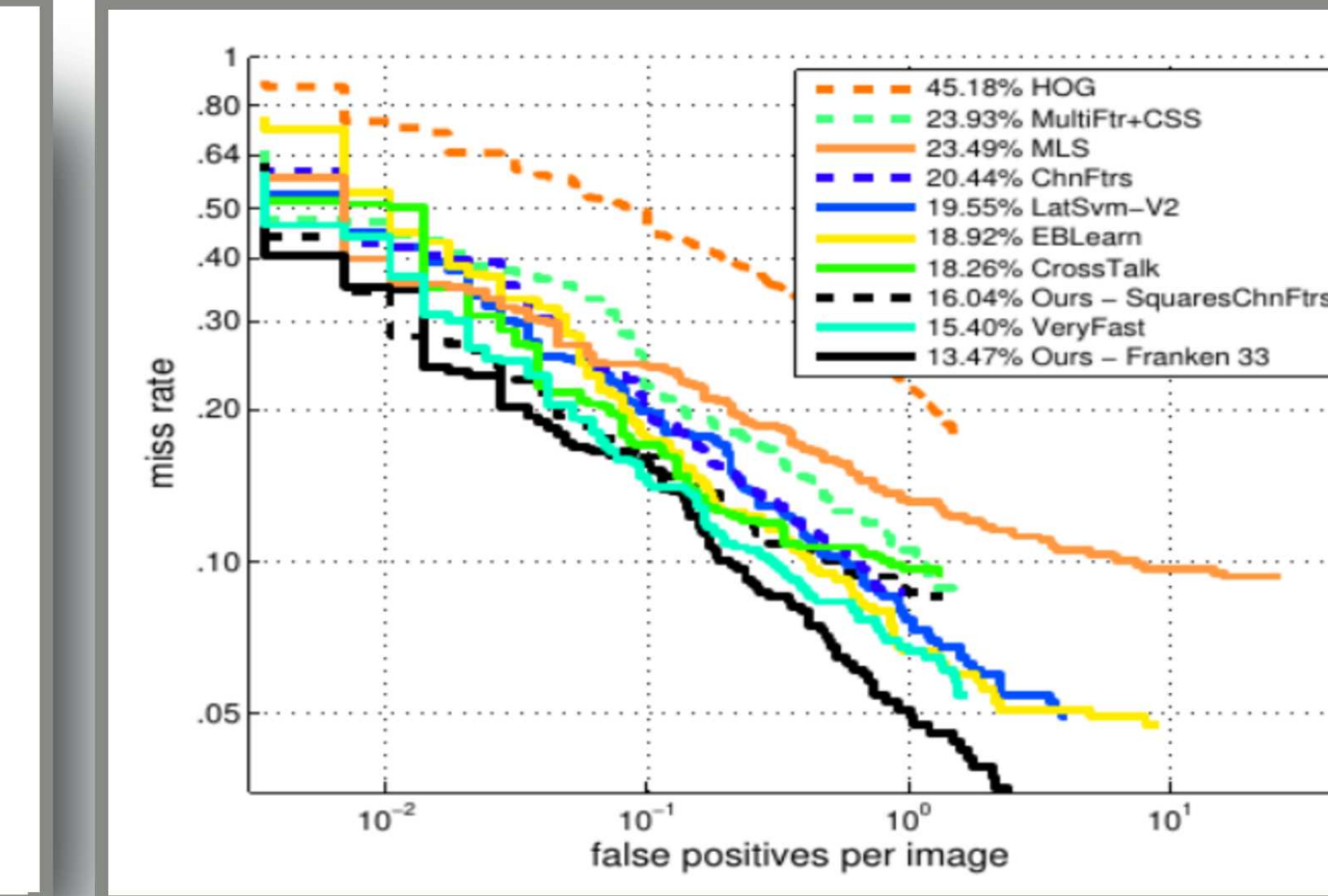
How good do all 33 classifiers perform jointly?

- Different types of occlusion classifiers share at least 1000 features
- Joint non-maximum suppression possible
- Sublinear in number of occlusion specific classifiers

Caltech (occluded)



INRIA



ETH

